



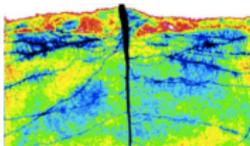
A. Kaestner :: Paul Scherrer Institut

Bimodal imaging with neutrons

- 1 Introduction
- 2 Some considered modalities
- 3 Acquisition
- 4 Image fusion
- 5 Applications
- 6 Summary and discussion

# Introduction

## Hydrology



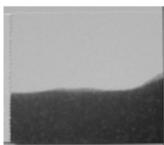
- Segmentation accuracy
- Estimate water content

## Cultural heritage



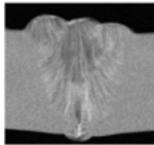
- Segmentation accuracy
- Material classification

## Building materials



- Estimate water content
- Dimensional changes

## Materials science



- Penetration power
- Ambiguous readings

## Reasons to select or reject a specific imaging method

### Advantages

- Good transmission
- Good contrast
- Relevant features visible
- Materials can be identified

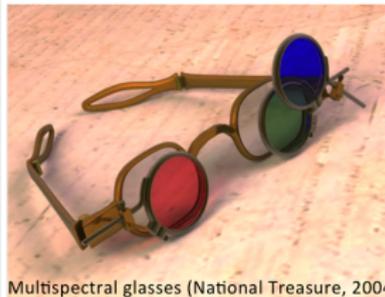
### Disadvantages

- Low transmission
- Low contrast
- Not all features visible
- Ambiguous response

## Purpose of multi-modality

*Match the advantages of each method against the disadvantages of the other methods to obtain more information than using each method individually.*

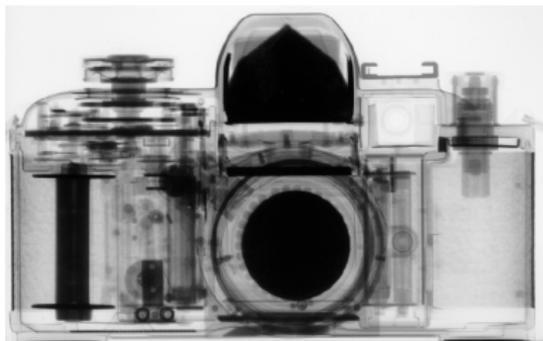
- 1 Extend range of operation.
- 2 Extend spatial and temporal coverage.
- 3 Reduce uncertainty.
- 4 Increase reliability.
- 5 Robust system performance.



Multispectral glasses (National Treasure, 2004)

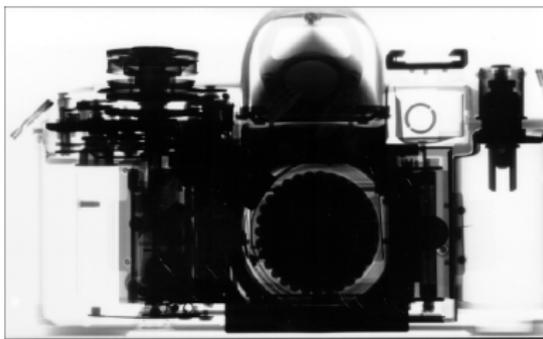
# Some considered modalities

## Neutrons



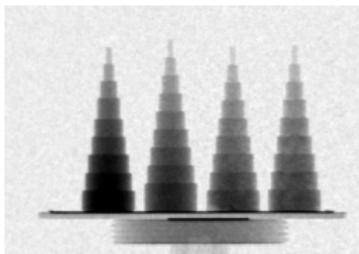
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1	H 1.00																	He 0.02	
2	Li 3.30	Be 2.79											B 10.14	C 10.96	N 0.45	O 0.17	F 0.20	Ne 0.19	
3	Na 0.99	Mg 0.15											Al 0.11	Si 0.11	P 0.12	S 0.08	Cl 1.23	Ar 0.09	
4	K 0.06	Ca 0.08	Sc 2.05	Ti 0.60	V 0.72	Cr 3.54	Mn 1.21	Fe 1.19	Co 3.32	Ni 2.95	Cu 1.87	Zn 0.35	Ga 0.40	Ge 0.47	As 0.67	Se 0.75	Br 0.24	Kr 0.61	
5	Rb 0.08	Sr 0.14	Y 0.27	Zr 0.29	Nb 0.48	Mo 0.52	Tc 1.78	Ru 0.53	Rh 10.68	Pd 0.78	Ag 0.94	Cd 115.1	In 7.56	Sn 10.21	Sb 0.30	Te 0.25	I 0.23	Xe 0.43	
6	Cs 0.28	Ba 0.07		Hf 1.49	Ta 1.49	W 3.47	Re 0.93	Os 2.28	Ir 30.46	Pt 17.46	Au 0.23	Hg 18.21	Tl 8.47	Pb 0.38	Bi 0.27	Po -	At -	Rn -	
7	Fr 0.94	Ra -		Rf -	Db -	Sg -	Bh -	Hs -	Mt -	Ds -	Rg -	Uub -	Uut -	Uuq -	Uup -	Uuu -	Uuq -	Uuo -	
Lanthanides																			
		La 0.52	Ce 0.14	Pr 0.41	Nd 0.87	Pm 1.71	Sm 171.47	Eu 54.54	Gd 149.0	Tb 93.3	Dy 92.42	Ho 122.5	Er 144	Tm 151	Yb 140	Lu 2.75			
Actinides																			
			Ac 0.58	Th 0.46	Pa 0.82	U 1.89	Np 55.52	Pu 12.88	Am -	Cm -	Bk -	Cf -	Es -	Fm -	Md -	No -	Lr -		

## X-rays

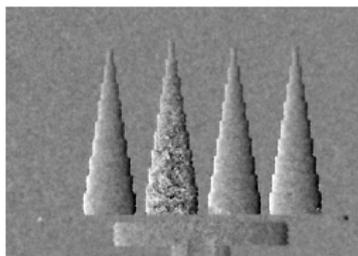


Group ↓	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	
1	H 0.02																	He 0.02	
2	Li 0.06	Be 0.22											B 0.28	C 0.27	N 0.11	O 0.16	F 0.14	Ne 0.17	
3	Na 0.15	Mg 0.04											Al 0.33	Si 0.25	P 0.25	S 0.36	Cl 0.23	Ar 0.20	
4	K 0.14	Ca 0.26	Sc 0.48	Ti 0.75	V 1.04	Cr 1.28	Mn 1.32	Fe 1.57	Co 1.78	Ni 1.96	Cu 1.97	Zn 1.64	Ga 1.42	Ge 1.53	As 1.50	Se 1.23	Br 0.96	Kr 0.73	
5	Rb 0.47	Sr 0.86	Y 1.61	Zr 2.47	Nb 3.43	Mo 4.29	Tc 5.95	Ru 5.73	Rh 6.98	Pd 6.13	Ag 5.97	Cd 4.94	In 4.31	Sn 3.98	Sb 4.28	Te 4.06	I 3.45	Xe 2.53	
6	Cs 1.47	Ba 2.73		Hf 16.70	Ta 25.42	W 30.49	Re 34.47	Os 37.32	Ir 39.01	Pt 36.61	Au 32.94	Hg 29.89	Tl 23.23	Pb 22.41	Bi 20.38	Po -	At -	Rn -	
7	Fr 15.80	Ra -		Rf -	Db -	Sg -	Bh -	Hs -	Mt -	Ds -	Rg -	Uub -	Uut -	Uuq -	Uup -	Uuu -	Uuq -	Uuo -	
Lanthanides																			
		La 5.08	Ce 0.78	Pr 0.23	Nd 0.46	Pm 1.32	Sm 7.68	Eu 5.66	Gd 6.69	Tb 9.46	Dy 10.17	Ho 10.11	Er 11.70	Tm 12.44	Yb 6.32	Lu 14.07			
Actinides																			
			Ac 14.47	Th 28.88	Pa 39.85	U 49.88	Np -	Pu -	Am -	Cm -	Bk -	Cf -	Es -	Fm -	Md -	No -	Lr -		

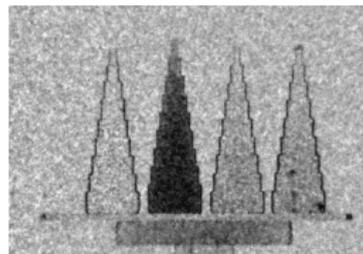
Transmission



Differential phase

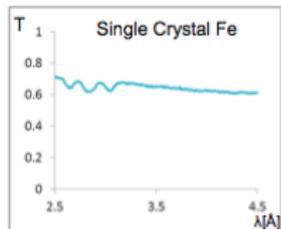
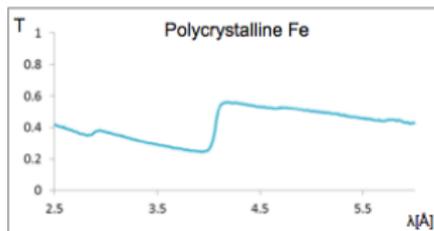
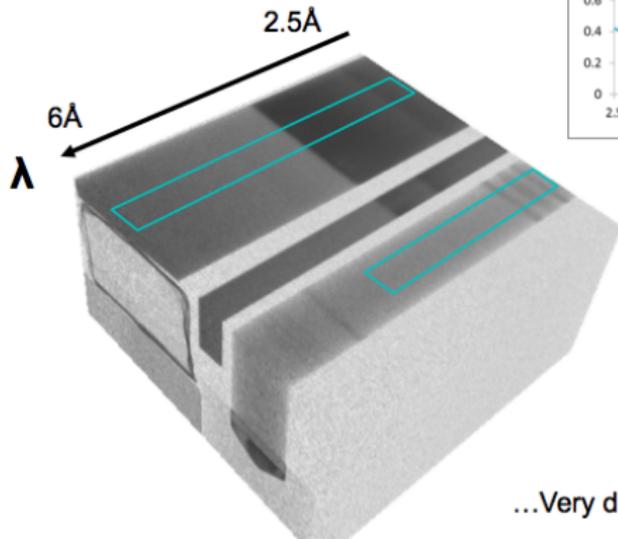


Dark field



- Data comparable on pixel level
- Non-linear relation between the variables.
- Improved estimation schemes using iterative process
- Physical interpretation/motivation to fuse?

## A closer look at the iron samples

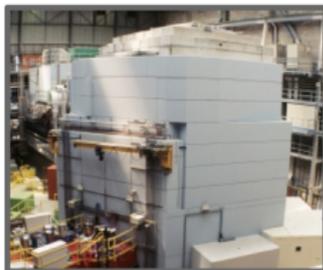


...Very different wavelength dependence

- Material analysis
- Selector calibration

# Acquisition

# Different approaches to NX-imaging: Off-site



Neutrons



## Synchrotron



OR



Lab-based X-ray

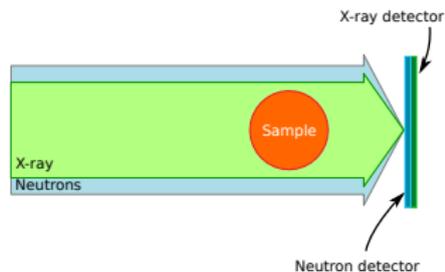
## Pros

- Different resolutions
- Optimized acquisition times
- Access to equipment

## Cons

- Sample transport (sample activation etc.)
- No simultaneous acquisition
- Coordination of beamtime

## Inline – NEUTRA



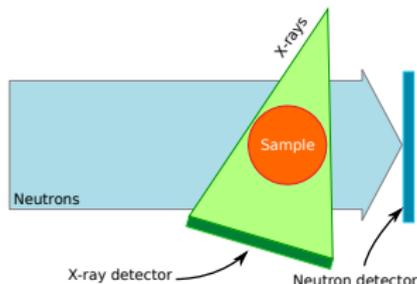
### Pros

- Same detector
- Pixel-wise comparable
- Sample is not repositioned
- Strong X-ray source

### Cons

- No simultaneous acquisition

## Perpendicular – ICON

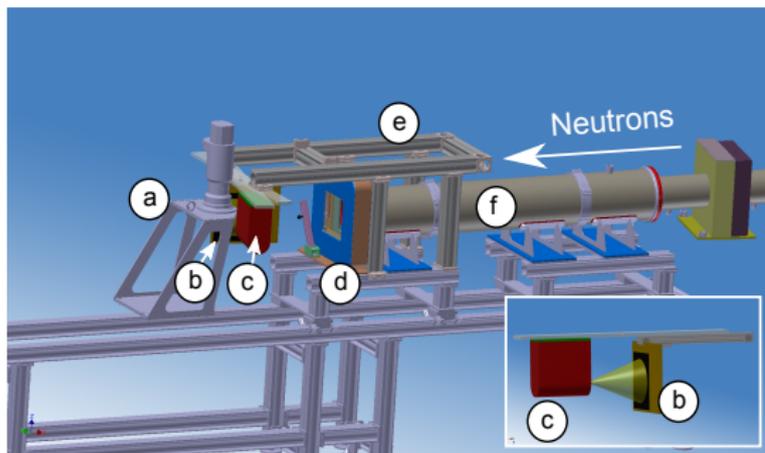


### Pros

- Optimized detectors
- Magnification (X-rays)
- Simultaneous acquisition
- Sample is not repositioned

### Cons

- Different coordinate systems



## Components

- a X-ray source
- b Neutron flight tube
- c Beam limiter
- d Midi camera box
- e Maxi camera box
- f Sample environment

## Neutrons

- Cold neutron spectrum
- Almost parallel beam
- Camera/Scintillator

## X-rays

- 150kV, 75W source
- Cone beam ( $42^\circ$ )
- Flat panel detector

[?]

## Considerations for the acquisition

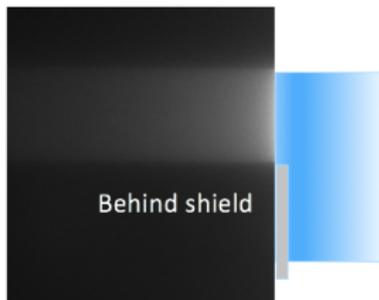
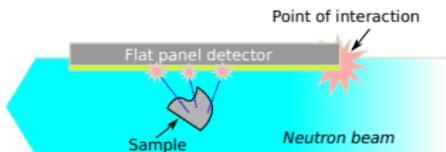
**Interference** The cross-talk between modalities must be minimized

**Time** To observe processes – when are the data acquired.

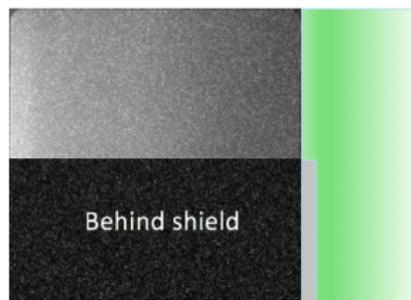
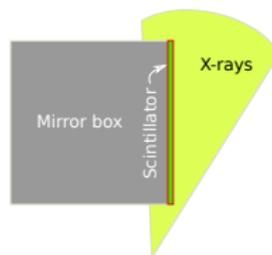
**Resolution** Resolution of the modalities

**Magnification** Beam divergence of the modalities.

## Neutrons on X-ray detector

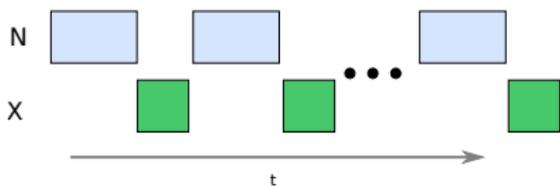


## X-rays on Neutron detector



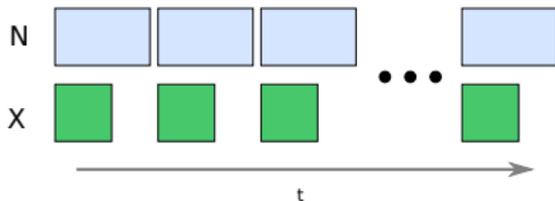
## Alternating sequence

- One modality active
  - Full scan
  - Alternating
- Cross-talk is minimized
- Two acquisition position possible
- Longer delays



## Parallel sequence

- Both modalities active
- Shielding required
- Single acquisition position only
- Rapid acquisition



## What limits the volume rate?

Sample stage

Sample stability

Detector sensitivity

Detector frame rate

Low radiation dose – low SNR

# Image fusion

## Definition

The theory, techniques and tools which are used for combining sensor data, or data derived from sensory data, into a common representational format.

## Aim

To improve the quality of the information, so that it is, in some sense, better than would be possible if the data sources were used individually.

[Mitchell, 2012]

## Fusion strategies

**Multivariate fusion** All data are combined using the same concept.

**Augmented fusion** Modalities have different functions in the fusion process.

**Artifact reduction by fusion** The second modality can be used to fill in the blanks.

**Combination** One method may not give the final result – combination

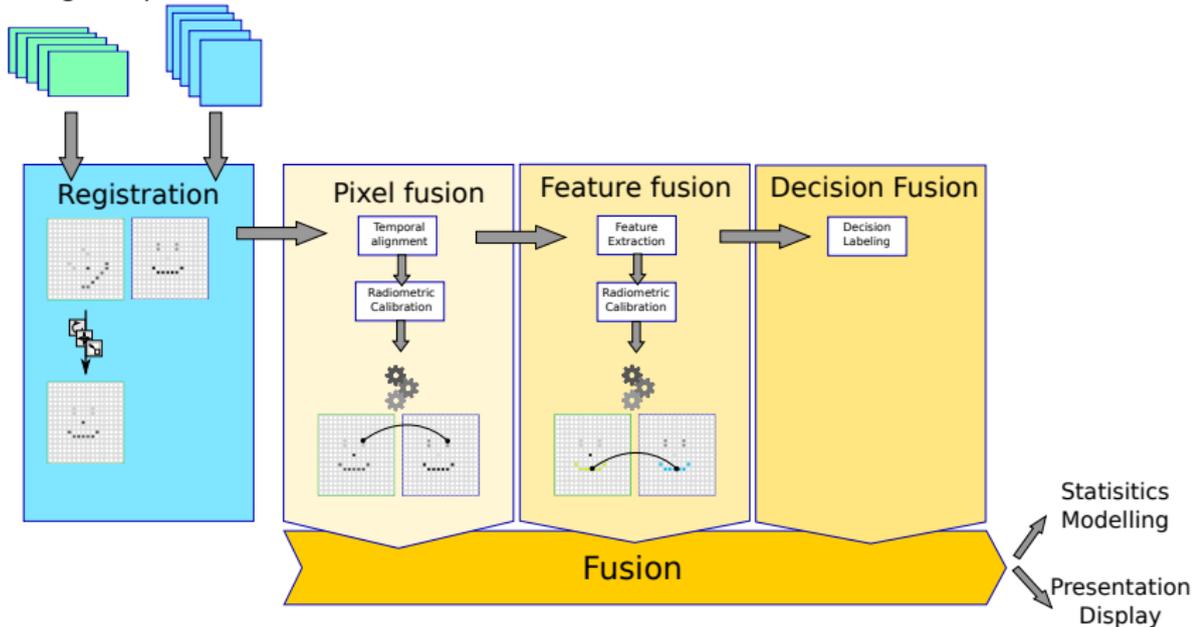
## Select strategy

The fusion strategy determined by:

- Sample composition
- Experiment objectives
- Condition of the data

## Image fusion workflow

Image acquisition



[Goshtasby, 2012],[Mitchell, 2010]

## Definition

The combination perform worse than the individual modalities.

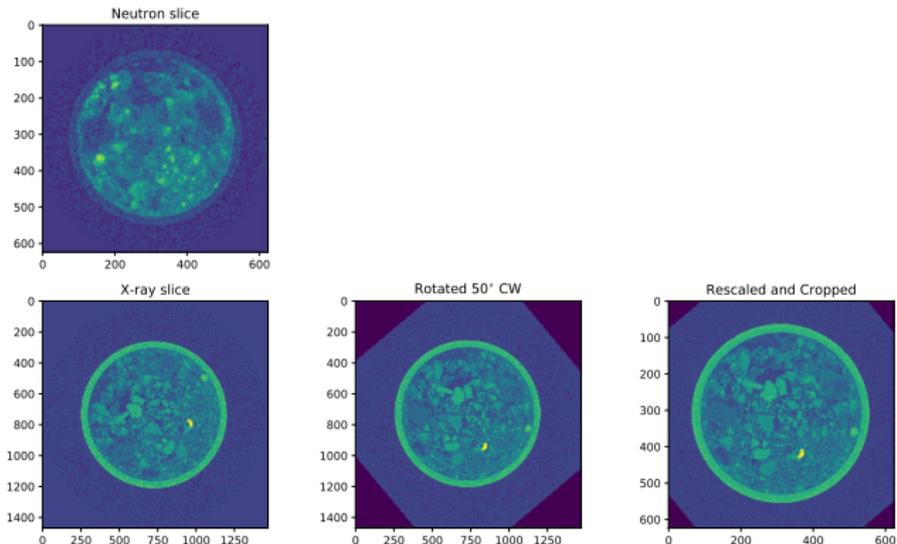
This can be caused by

- Selection of the wrong variables.
- Too complex combination.
- Sensor information canceling each other.



## The process

A series of affine transformations to bring images on the same grid.



Registration is an optimization problem with many local minima.

- Manual or guided registration
  - Perform the full transformation manually
  - Identify land marks, points, lines, planes
  - Provide a coarse preregistration
- Automatic registration
  - Iterative process
  - Metrics
  - Multi-modality loose common landmarks

[Goshtasby, 2012]

Use e.g. VG Studio to

- Register data sets
- Interactive guided segmentation of the separate data sets.

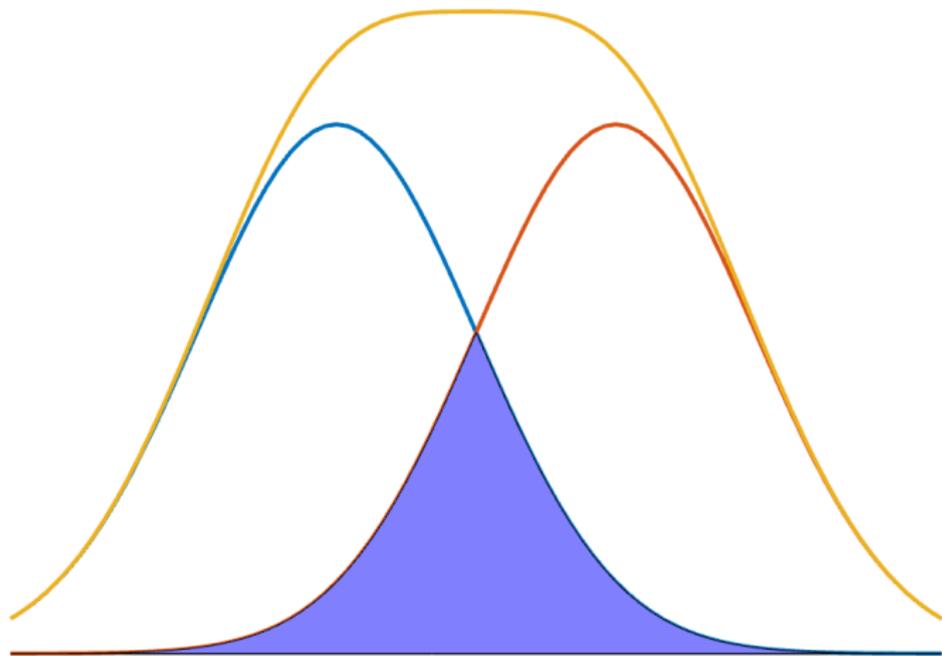
Neutrons



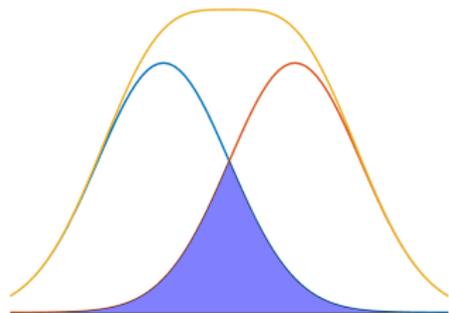
X-rays



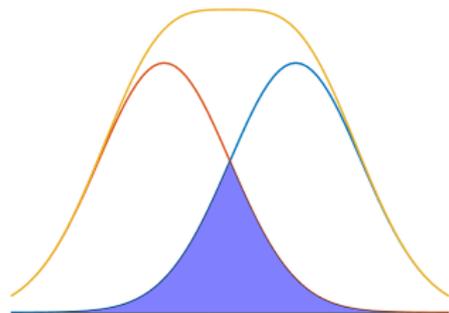
[Mannes et al., 2015]

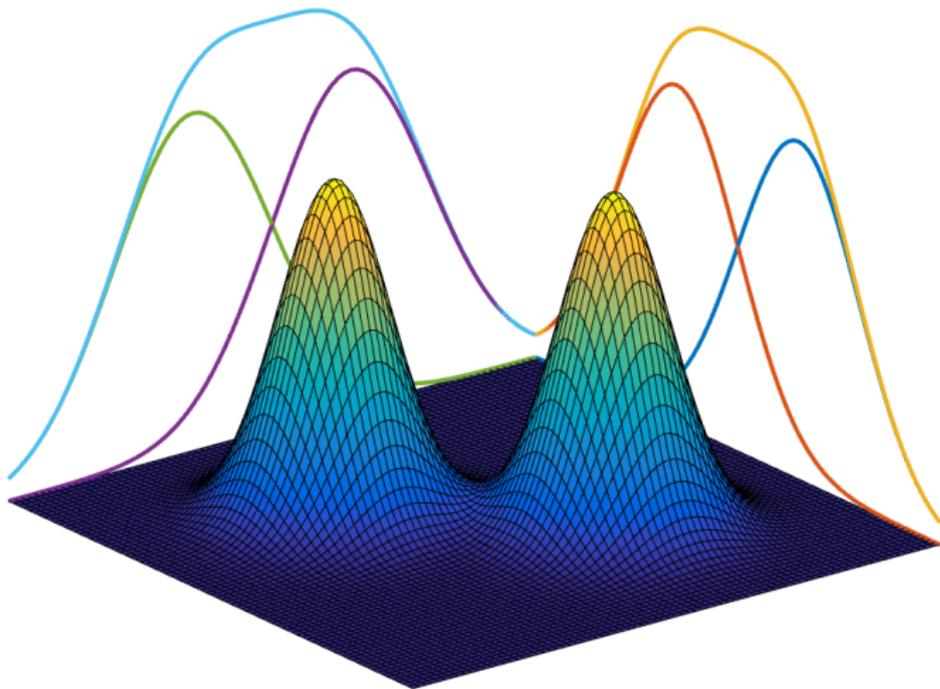


Modality A

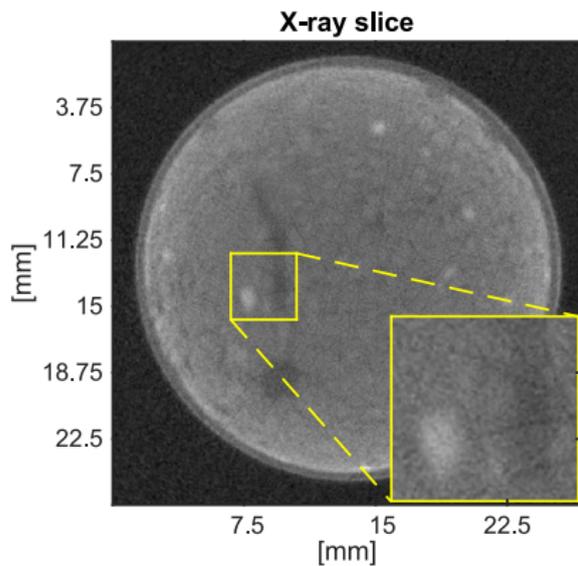
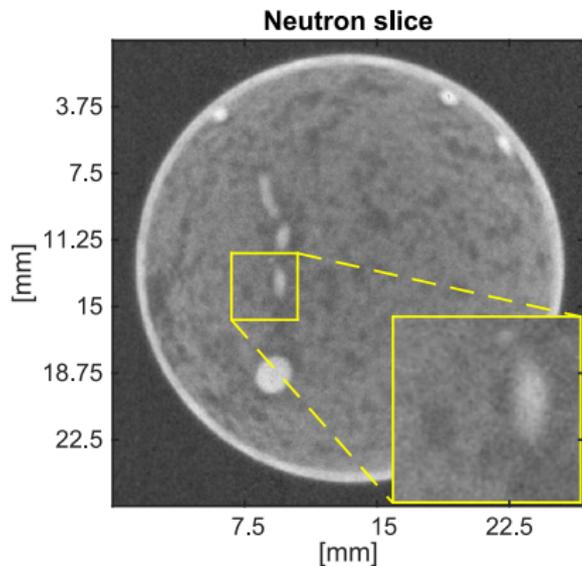


Modality B

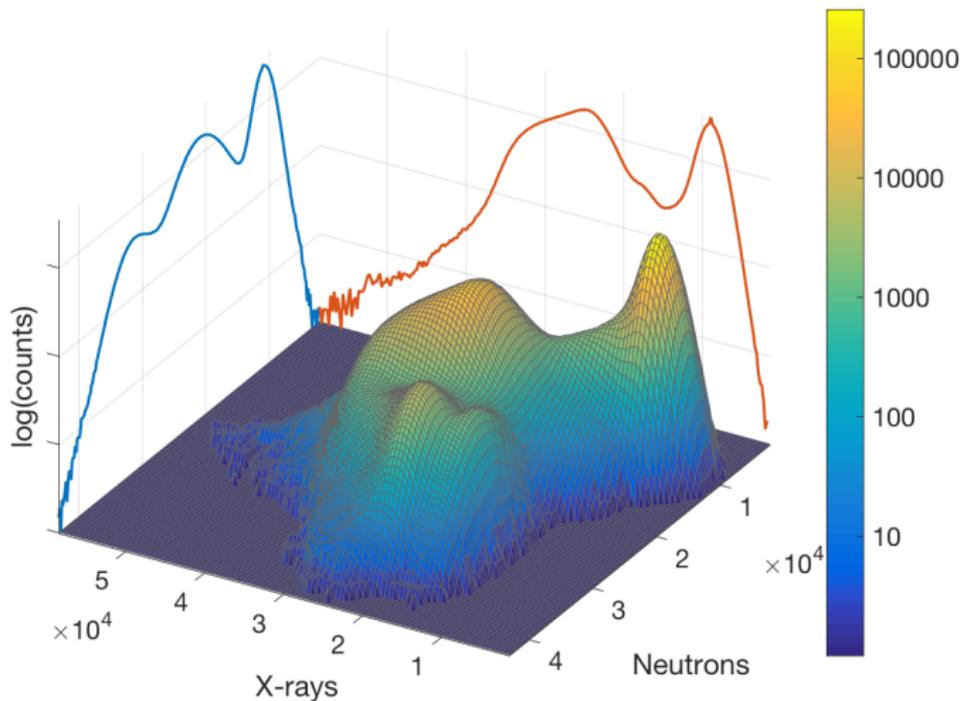




# Example: Roots in soil



## Bivariate histogram of roots



## Data

- Images from  $M$  modalities  
 $f_1, \dots, f_M$
- Registered
- Artifact corrected

## Classes

The  $N$  classes are described by:

$$\mathcal{H}_1 : p(\mu_1, \Sigma_1)$$

$$\mathcal{H}_2 : p(\mu_2, \Sigma_2)$$

$$\vdots$$

$$\mathcal{H}_N : p(\mu_N, \Sigma_N)$$

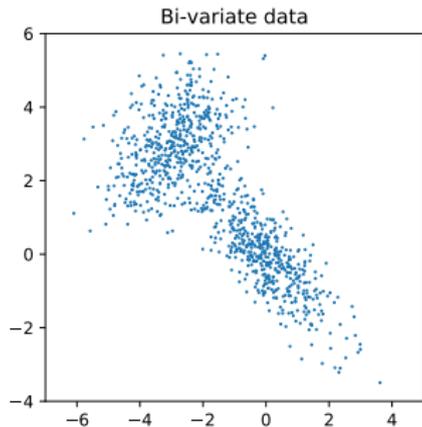
## Gaussian mixture model

With Gaussian distribution we can describe the bivariate histogram using:

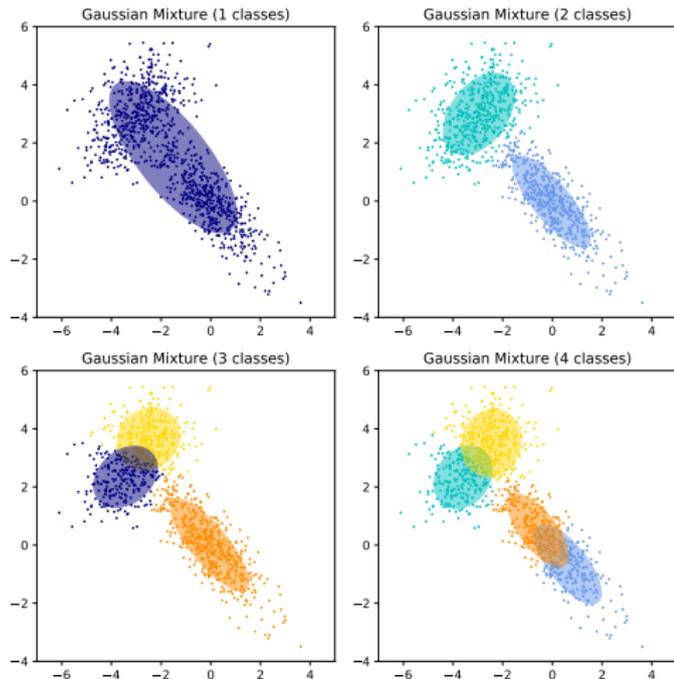
$$p(\theta) = \sum_1^N \phi \mathcal{N}(\mu_i, \Sigma_i)$$

[Duda et al., 2001]

## Bivariate data



## Gaussian mixture model fitting



For a set of multivariate normal distributions  $p_i = \mathcal{N}(\mu_i, \Sigma_i)$

Euclidean

$$D_E = \sqrt{(x - \mu_1)^T \cdot (x - \mu_1)}$$

Mahalanubis Distance from class  $i$  to point  $x$

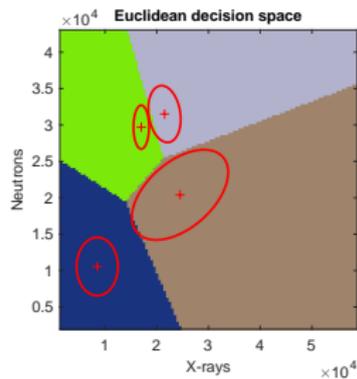
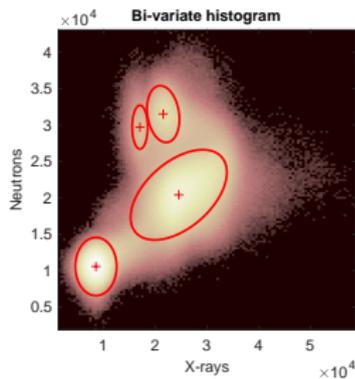
$$D_M = \sqrt{(x - \mu_i)^T \Sigma_i (x - \mu_i)}$$

Bhattacharia Distance between two classes

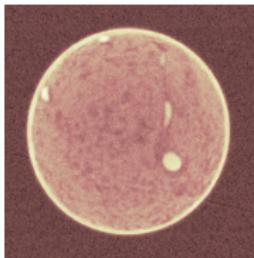
$$D_B = \frac{1}{8} (\mu_1 - \mu_2)^T \Sigma (\mu_1 - \mu_2) + \frac{1}{2} \ln \left( \frac{|\Sigma|}{\sqrt{|\Sigma_1| \cdot |\Sigma_2|}} \right)$$

Assign the point to the class with shortest distance.

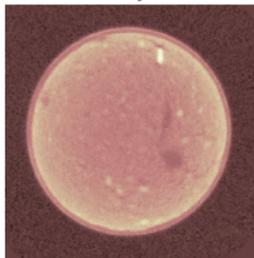
# Segmentation by Euclidean distance



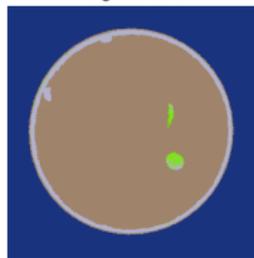
Neutrons



X-rays



Segmentation



## Beer–Lamberts law

$$I = I_0 e^{-\frac{\rho}{A} N_A \sigma x} \quad (2)$$

$\rho$  Material density

$A$  Atomic weight

$\sigma$  microscopic cross section

- Probability of interaction
- modality dependent

$x$  propagation length

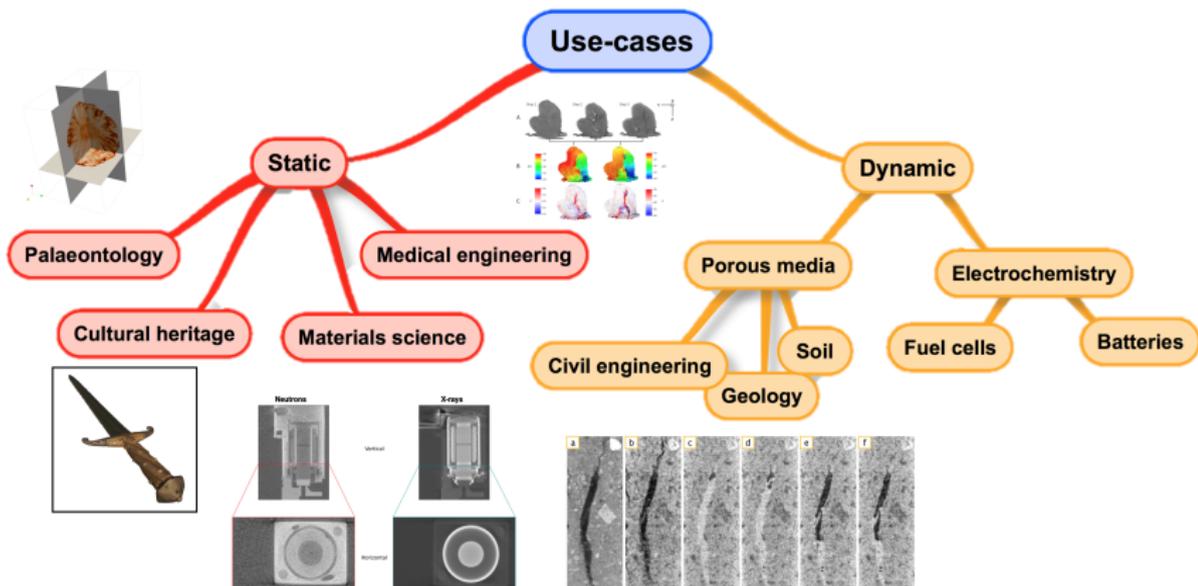
## Equation system

$$\sum_{i=1}^N \Sigma_i x_i = q_N$$

$$\sum_{i=1}^N \mu_i x_i = q_X \quad (3)$$

- attn coeff known  $\rightarrow$  estimate lengths.
- More pixels  $\rightarrow$  more materials.

# Applications



## NDT

- Function or production inspection
- Neutrons and X-rays

## Medical engineering

- Bone growth with implants
- Neutrons and X-rays

## Cultural heritage

- Ancient artifact inspection
- Neutrons and X-rays

## Material science

- Texture contrast
- Multi energy fusion

## Corroding nails



## Desalinisation bath



## Evaluation of desalinisation process by imaging

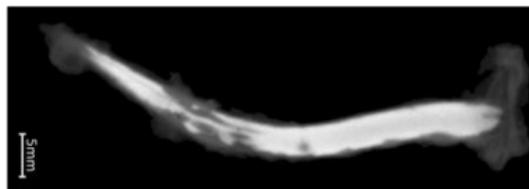
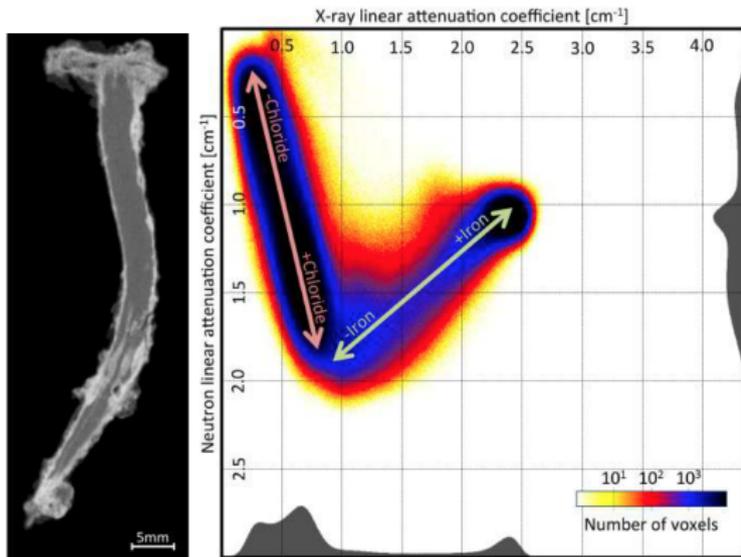
- Corrosion products have low density but contain H
- Hard to separate components

⇒ Bimodal imaging helps

[Jacot-Guillarmod et al., 2018]

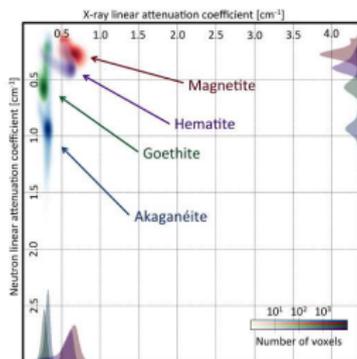
# Nails – images and histogram

Neutron CT

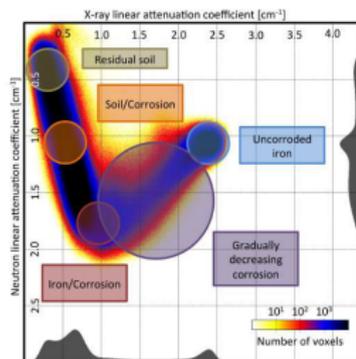


X-ray CT

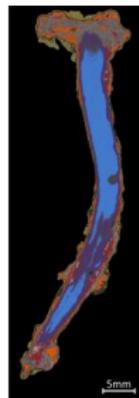
## Components



## Nail histogram



## Classified regions



## Conclusion

- Bimodal imaging made it possible to verify the effect of desalination.

## Porous media

- Soil and roots
- Civil engineering
- Cultural heritage/preservation

## Foams

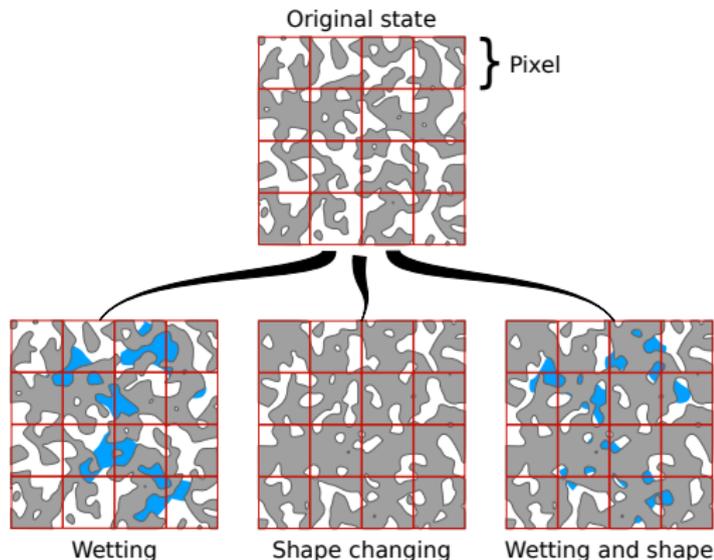
- Food
- Construction materials

## The problem

- More than one component changes over time, e.g. shape and composition.
- A single modality can't tell what changed.

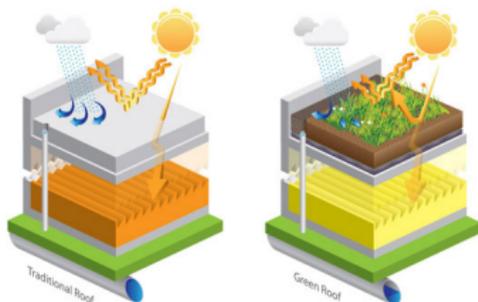
## Partial volume effects

- Pore can't be resolved
- Contributions unknown
- Changes with time



## Urban vegetation

Green Roof Comparison



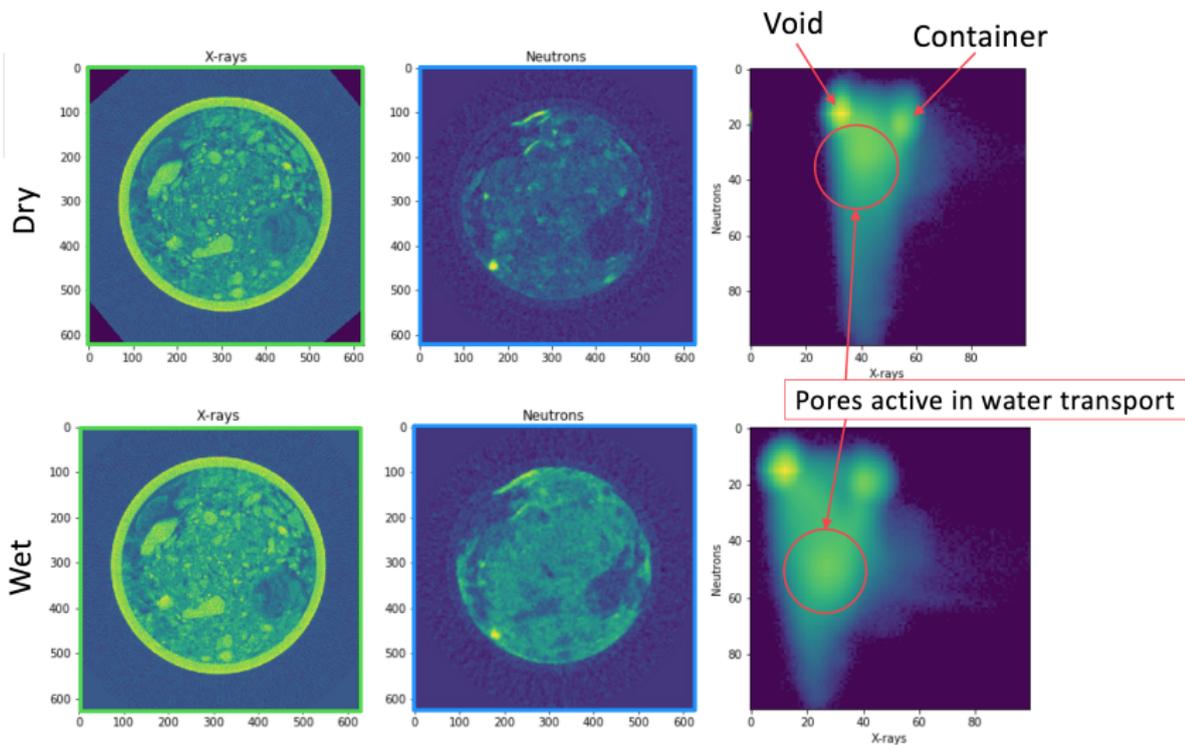
- Controls urban climate
- Controls building environment
- Reduces excess rain water

## Experiment

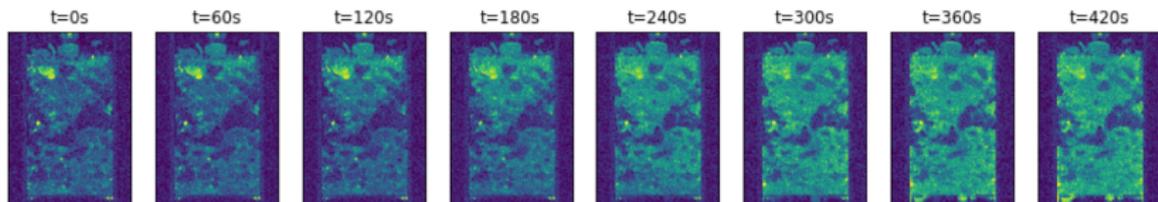


- Early pedogenesis
- Water flow – imbibition
- Soil formation

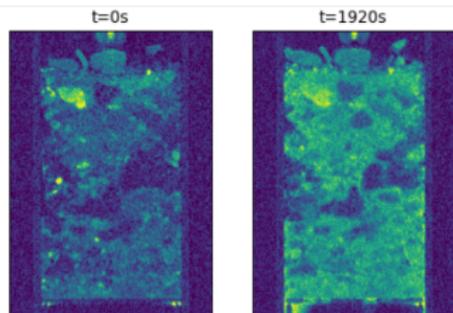
[Kaestner et al., 2018]



## Wetting front



## Sample swelling



## Next steps

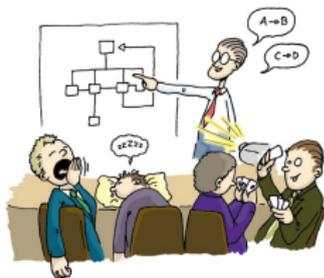
- Quantify water content
- Analyze displacements
- System modeling

# Summary and Discussion

## Multimodal imaging. . .

- Is a combination of several methods
- Requires planning and development of experiment strategies
  - Understanding of the underlying physics.
  - Optimized acquisition.
  - Dedicated analysis strategies.
  - Choices are application oriented.
- We have the instrumentation
- Data fusion theory exists, but needs to be explored for NI

I'm done



Your turn





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